

# REVIEW PROBLEMS

1.  $\frac{dx}{dt} = 10 - x^2 - y^2$

$\frac{dy}{dt} = 3x - y$

(a) Equilibrium points:

$\frac{dy}{dt} = 0 \Rightarrow y = 3x$   
 $\frac{dx}{dt} = 0 \Rightarrow 10 - x^2 - (3x)^2 = 0$   
 $10 - 10x^2 = 0$   
 $x^2 = 1$   
 $x = \pm 1$   
 $x = 1 \Rightarrow y = 3; \quad x = -1 \Rightarrow y = -3$

Equilibrium Points:  $(1, 3), (-1, -3)$

Jacobian:  $J(x, y) = \begin{bmatrix} -2x & -2y \\ 3 & -1 \end{bmatrix}$

$J(1, 3) = \begin{bmatrix} -2 & -6 \\ 3 & 1 \end{bmatrix}$  has eigenvalues  $\lambda = \frac{-3 \pm i\sqrt{71}}{2}$

so  $(1, 3)$  is a spiral sink

$J(-1, -3) = \begin{bmatrix} 2 & 6 \\ 3 & -1 \end{bmatrix}$  has eigenvalues  $\lambda = -4, \lambda = 5$

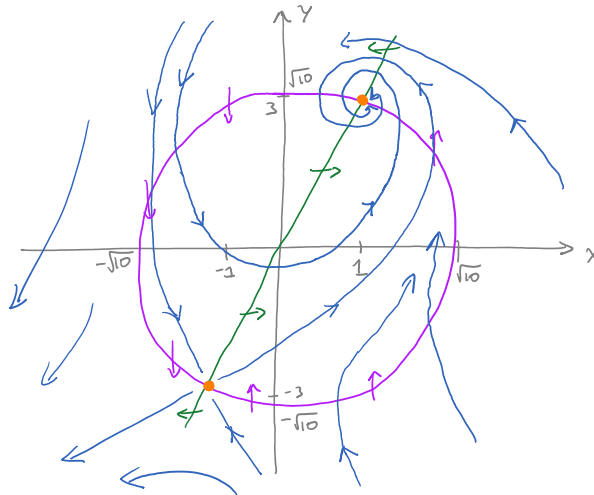
so  $(-1, -3)$  is a saddle

(b) Nullclines:

x-nullcline:  $x^2 + y^2 = 10$

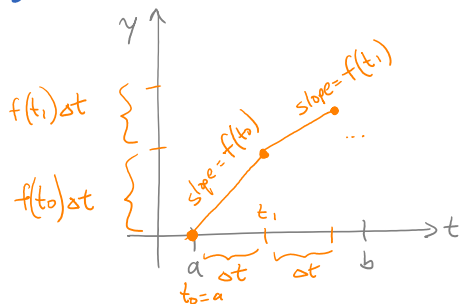
y-nullcline:  $y = 3x$

Phase portrait:



2.  $\frac{dy}{dt} = f(t), \quad y(a) = 0$

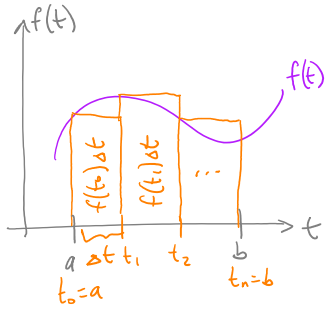
(a) Euler's method:



$y(b) \approx f(t_0)\Delta t + f(t_1)\Delta t + \dots + f(t_{n-1})\Delta t$

$y(b) \approx \sum_{k=0}^{n-1} f(t_k)\Delta t$

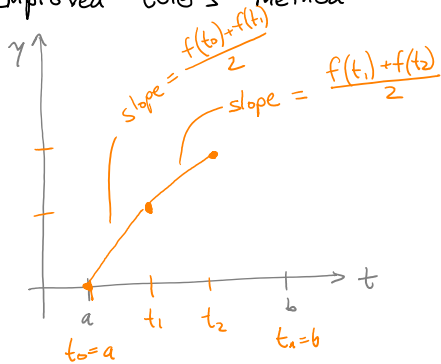
Approximating  $\int_a^b f(t) dt$  by left Riemann sums



$$\int_a^b f(t) dt \approx f(t_0)\Delta t + f(t_1)\Delta t + \dots + f(t_{n-1})\Delta t$$

$$\int_a^b f(t) dt \approx \sum_{k=0}^{n-1} f(t_k) \Delta t$$

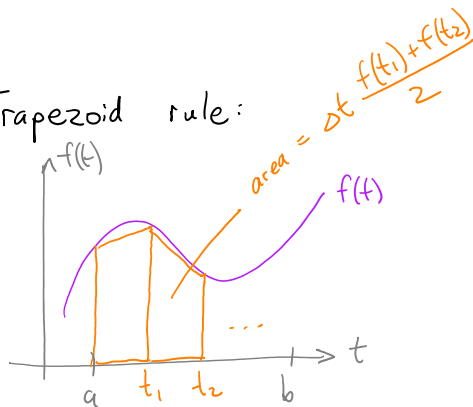
(b) Improved Euler's method:



$$y(b) \approx \Delta t \frac{f(t_0) + f(t_1)}{2} + \Delta t \frac{f(t_1) + f(t_2)}{2} + \dots + \Delta t \frac{f(t_{n-1}) + f(t_n)}{2}$$

$$\approx \sum_{k=0}^{n-1} \Delta t \frac{f(t_k) + f(t_{k+1})}{2}$$

Trapezoid rule:



$$\int_a^b f(t) dt \approx \Delta t \frac{f(t_0) + f(t_1)}{2} + \dots + \Delta t \frac{f(t_{n-1}) + f(t_n)}{2}$$

$$\approx \sum_{k=0}^{n-1} \Delta t \frac{f(t_k) + f(t_{k+1})}{2}$$